## Thomas Kehoe Prof. Little Math 136 2 April 2014

## with(*DEtools*);

[AreSimilar, Closure, DEnormal, DEplot, DEplot3d, DEplot polygon, DFactor, DFactorLCLM, DFactorsols, Dchangevar, Desingularize, FunctionDecomposition, GCRD, Gosper, Heunsols, Homomorphisms, IVPsol, IsHyperexponential, LCLM, MeijerGsols, MultiplicativeDecomposition, ODEInvariants, PDEchangecoords, PolynomialNormalForm, RationalCanonicalForm, ReduceHyperexp, RiemannPsols, Xchange, Xcommutator, Xgauge, Zeilberger, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsvm, canoni, caseplot, casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys, dalembertsol, dcoeffs, de2diffop, dfieldplot, diff table, diffop2de, dperiodic sols, dpolyform, dsubs, eigenring, endomorphism charpoly, equiny, eta k, eulersols, exactsol, expsols, exterior power, firint, firtest, formal sol, gen exp, generate ic, genhomosol, gensys, hamilton eqs, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate sols, intfactor, invariants, kovacicsols, leftdivision, liesol, line int, linearsol, matrixDE, matrix riccati, maxdimsystems, moser reduce, muchange, mult, mutest, newton polygon, normalG2, ode int y, ode y1, odeadvisor, odepde, parametricsol, particularsol, phaseportrait, poincare, polysols, power equivalent, rational equivalent, ratsols, redode, reduceOrder, reduce order, regular parts, regularsp, remove RootOf, riccati system, riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, singularities, solve group, super reduce, symgen, symmetric power, symmetric product, symtest, transinv, translate, *untranslate*, *varparam*, *zoom*]

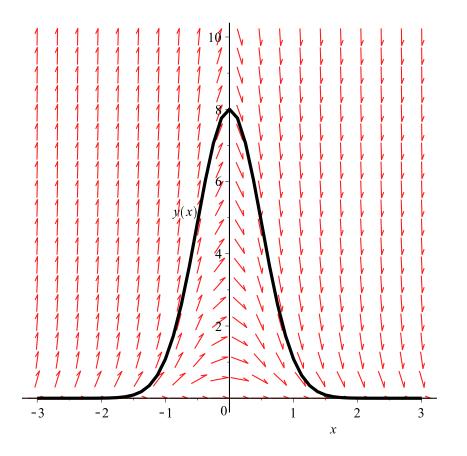
## with(plots);

[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d, conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot, display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot, implicitplot3d, inequal, interactive, interactiveparams, intersectplot, listcontplot, listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple, odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d, polyhedra\_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions, setoptions3d, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]

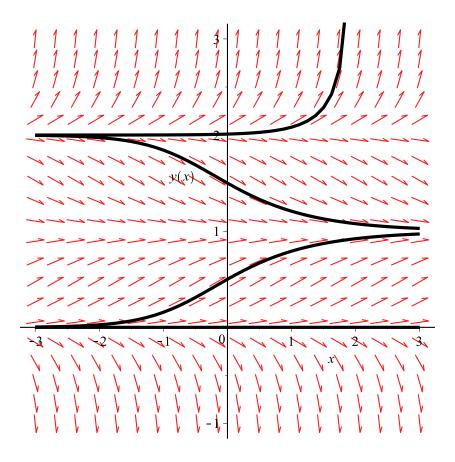
# I.A)

 $DEplot(diff(y(x), x) = -4x \cdot y(x), y(x), x = -3..3, [y(0) = 8], y = 0..10, linecolor = black);$ 

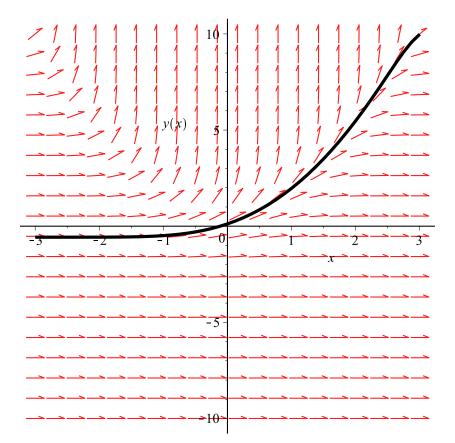
(2)



I.B)  $DEplot(diff(y(x), x) = y(x) \cdot (y(x) - 1) \cdot (y(x) - 2), y(x), x = -3 ..3, [y(0) = 0, y(0) = 0.5, y(0) = 1.5, y(0) = 2.01], y = -1 ..3, linecolor = black);$ 



I.C)  $DEplot(diff(y(x), x) = \exp(-x^2 + y(x)), y(x), x = -3..3, [y(-3) = -.572369], y = -10..10, linecolor = black);$ 



II.D) Yes because if one looks at the slope fields of A, B and C, one can see that they all have asymptopes where f'(x) of the differential equation=0 (AKA where f'(x)switches from positive to negative or vice versa) and therefore, one can see the gerenal shape of the graph.

II.E) The cut off value is approximately -.572369. So  $y_0 \ge -.572369$  will approach a limit of infinity.

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III.A)

xl[0] := 0: yl[0] := 8:

for i to 4 do

xl[i] := xl[i-1] + .25;

yl[i] := yl[i-1] - 4 xl[i-1] \cdot yl[i-1] \cdot (0.25);

end do;

0.25

8.

0.50

6.0000

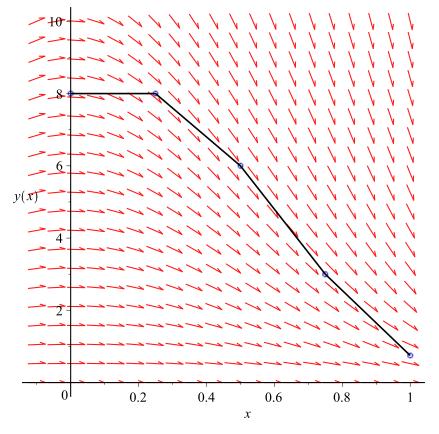
0.75

3.00000000

1.00
```

### 0.75000000

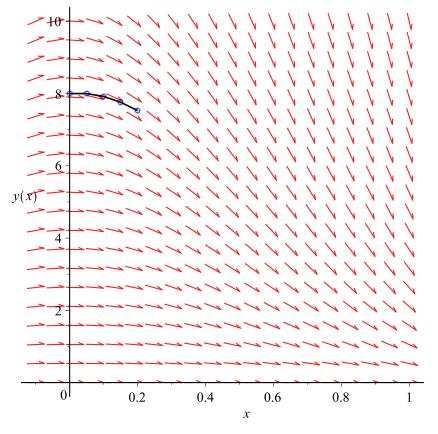
 $\begin{array}{l} DirField := DEplot(diff(y(x), x) = -4 \cdot x \cdot y(x), [y(x)], x = -.1 ..1, y = 0 ..10):\\ Pts := plot([seq([xl[i], yl[i]], i = 0 ..4)], style = point, symbol = circle, color = blue):\\ Lines := plot([seq([xl[i], yl[i]], i = 0 ..4)], color = black):\\ display(DirField, Pts, Lines); \end{array}$ 



III.B) xl[0] := 0 : yl[0] := 8 :for *i* to 4 do xl[i] := xl[i-1] + 0.05;  $yl[i] := yl[i-1] - 4 xl[i-1] \cdot yl[i-1] \cdot (0.05);$ end do;

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 $\begin{array}{l} DirField \coloneqq DEplot(diff(y(x), x) = -4 \cdot x \cdot y(x), [y(x)], x = -.1 \dots 1, y = 0 \dots 10) :\\ Pts \coloneqq plot([seq([xl[i], yl[i]], i = 0 \dots 4)], style = point, symbol = circle, color = blue) :\\ Lines \coloneqq plot([seq([xl[i], yl[i]], i = 0 \dots 4)], color = black) :\\ display(DirField, Pts, Lines); \end{array}$ 



III.C) It seems like the pattern is every odd i there is an underestimate. The property of the line givern by Euler's method which indicates that it is an underestimate is when it is below the corresponding points given by the slope field and when it's above those slope field points there is an overestimate indicated. See graphs in III.A and III.B for illustration of these properties.