

College of the Holy Cross, Fall 2018
Math 244, Homework 7

1. Define

$$A = \begin{bmatrix} 2 & 1 \\ -2 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 6 \\ 5 & -1 & 2 \end{bmatrix} \quad C = \begin{bmatrix} 7 & 2 \\ 1 & 1 \\ -2 & 4 \end{bmatrix} \quad D = \begin{bmatrix} 5 & 1 & 3 \\ 2 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

There are 16 possible matrix products that can be formed by multiplying these matrices by one another (AA, AB, AC, AD, \dots). Determine which of these are defined and compute them.

2. Let $\text{Proj}_{\mathbf{a}}(\mathbf{v}) = \left(\frac{\mathbf{v} \cdot \mathbf{a}}{\mathbf{a} \cdot \mathbf{a}} \right) \mathbf{a}$ denote the projection onto the line spanned by \mathbf{a} .

- (a) Prove that $\text{Proj}_{\mathbf{a}} \circ \text{Proj}_{\mathbf{a}} = \text{Proj}_{\mathbf{a}}$
- (b) Prove that $\text{Proj}_{\mathbf{a}}$ is not invertible.

3. Find the inverse of each matrix, or show that it is not invertible.

$$\begin{array}{lll} \text{(a)} \quad A = \begin{bmatrix} 3 & 6 \\ 1 & 2 \end{bmatrix} & \text{(c)} \quad C = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 9 \\ 1 & 8 & 27 \end{bmatrix} & \text{(e)} \quad E = \begin{bmatrix} 5 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \\ \text{(b)} \quad B = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} & \text{(d)} \quad D = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix} & \text{(f)} \quad F = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 2 & 3 & 4 \\ 0 & 0 & 3 & 4 \\ 0 & 0 & 0 & 4 \end{bmatrix} \end{array}$$

4. Let $\text{Rot}_{\theta} : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ denote counter-clockwise rotation through angle θ . Recall that its matrix with respect to the standard basis for \mathbf{R}^2 is $\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$.

- (a) Prove $\text{Rot}_{\theta} \circ \text{Rot}_{\phi} = \text{Rot}_{\theta+\phi}$.
- (b) Prove $(\text{Rot}_{\theta})^{-1} = \text{Rot}_{-\theta}$.

5. Let $\text{Ref}_{\theta} : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ denote reflection across the line that makes angle θ with the positive x -axis. In the notation of the text this is $R_{\mathbf{a}}$, where $\mathbf{a} = \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix}$.

- (a) Prove that the matrix for Ref_{θ} is $\begin{bmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{bmatrix}$.
- (b) Prove that $(\text{Ref}_{\theta})^{-1} = \text{Ref}_{\theta}$.
- (c) Prove that $\text{Ref}_{\theta} \circ \text{Ref}_{\phi}$ is a *rotation* through some angle. What angle?
- (d) Let $\text{Rot}_{\theta} : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ denote rotation through angle θ . Prove that $\text{Rot}_{\theta} \circ \text{Ref}_{\phi}$ is a reflection across some line. What line?

- (e) Prove that $\text{Ref}_\phi \circ \text{Rot}_\theta$ is a reflection across some line. What line?
6. Let $S : U \rightarrow V$ and $T : V \rightarrow W$ be linear transformations
- Prove that $\text{Im}(T \circ S) \subseteq \text{Im}(T)$. Give an example for which $\text{Im}(T \circ S) \neq \text{Im}(T)$.
 - Suppose S and T are invertible. Prove that $T \circ S$ is invertible and $(T \circ S)^{-1} = S^{-1} \circ T^{-1}$.
7. Let $V = P_3(\mathbf{R})$ and $W = P_4(\mathbf{R})$, and define $S : V \rightarrow W$ by $S(p(x)) = \int_0^x p(t) dt$ and $T : W \rightarrow V$ by $T(p(x)) = p'(x)$. Let $\alpha = \{1, x, x^2, x^3\}$ and $\beta = \{1, x, x^2, x^3, x^4\}$. Find $[S]_\alpha^\beta$, $[T]_\beta^\alpha$, $[S \circ T]_\beta^\beta$ and $[T \circ S]_\alpha^\alpha$.
8. Let $\alpha = \{\mathbf{u}_1, \mathbf{u}_2\}$ and $\alpha' = \{\mathbf{u}'_1, \mathbf{u}'_2\}$ be bases for \mathbf{R}^2 , where $\mathbf{u}_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$, $\mathbf{u}'_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, and $\mathbf{u}'_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$.
- Find the change of basis matrices $[I]_\alpha^{\alpha'}$ and $[I]_{\alpha'}^\alpha$.
 - Let β be the standard basis. Find $[I]_\alpha^\beta$ and $[I]_\beta^\alpha$.
 - Let $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ be the linear transformation such that $[T]_\alpha^\alpha = \begin{bmatrix} 5 & 0 \\ 0 & -3 \end{bmatrix}$. Find $[T]_{\alpha'}^{\alpha'}$.
 - Find $[T]_\beta^\beta$ where T is the transformation in part (c).