

Chapter 5 Topic Review Sheet

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This is a list of terminology and topics covered in the fifth chapter of *Calculus*, D. Hughes-Hallett, *et. al.* 3rd edition. Please consult the text for definitions, statements of properties, and numerous examples and exercises. Terms in bold face are defined in the text.

We covered all sections, 5.1 – 5.4.

Measuring Distance Traveled. (Section 5.1) When velocity is constant, the formula

$distance = velocity \cdot time$ allows us to compute distance travelled, given time. In this section, we use this formula to estimate distance, when velocity is not constant. Given velocity $v(t)$ measured every Δt seconds, we obtain upper and lower estimates on total distance traveled. We first plot the velocity data, connecting the points with a smooth curve. We estimate the area under this curve by adding up the area of rectangles of width Δt , and of height equal to the velocity measured at either the start of the interval (in a **left-hand sum**), or at the end of the interval (in a **right-hand sum**). Averaging the two estimates gives the best overall estimate. Moreover, if $v(t)$ is either increasing or decreasing on an interval $a \leq t \leq b$, the error involved in our left-hand or right-hand estimate is at most $|v(b) - v(a)| \cdot \Delta t$.

The Definite Integral (Section 5.2) In this section, we define the **definite integral** $\int_a^b f(x) dx$, where $f(x)$ is continuous on $[a, b]$. The function $f(x)$ is the **integrand**, and a and b are the **limits (or bounds) of integration**. The definite integral is defined as the limit of the left-hand or the right-hand **Riemann sums**, as the number of subintervals n goes to infinity. These sums are computed using the values of $f(x)$ at the points $a = x_0, x_1, \dots, x_{n-1}, x_n = b$ over n subintervals of equal length whose union is $[a, b]$. To get from one endpoint to the next, we add the increment $\Delta x = \frac{b-a}{n}$.

Using a specified number of subintervals for $[a, b]$, we may best estimate $\int_a^b f(x) dx$ by computing a left-hand Riemann sum, and a right-hand Riemann sum, and averaging the two. (This amounts to computing the sum using the **Trapezoid rule**.) We note that if $f(x)$ is decreasing on $[a, b]$, then the left-hand sum is an overestimate, while the right-hand sum is an underestimate. If $f(x)$ is increasing on $[a, b]$, these roles are reversed.

When $f(x)$ is positive on $[a, b]$, we interpret $\int_a^b f(x) dx$ as the area under the graph of f between a and b . If $f(x)$ is negative on $[a, b]$, then $\int_a^b f(x) dx$ is the *negative* of the area between the graph of f and the x -axis, between a and b . If $f(x)$ changes sign on $[a, b]$, then areas above the x -axis contribute positively, and areas below the x -axis contribute negatively to $\int_a^b f(x) dx$.

Interpretations of the Definite Integral. (Section 5.3) In this section, we discuss **total change** and **average value** of a function, in terms of definite integrals.

First, the total change in $F(t)$ between $t = a$ and $t = b$ is given by $\int_a^b F'(t) dt$. This relates to the Fundamental Theorem of Calculus, which is discussed in Section 5.4.

Second, the average value of $f(x)$ from $x = a$ to $x = b$ is given by $\frac{1}{b-a} \int_a^b f(x) dx$. In terms of the graph of $f(x)$, rearranging gives (average value of f on $[a, b]$) $\cdot (b - a) = \int_a^b f(x) dx$, so the average value of f is the height of a rectangle whose width is $b - a$ and whose area

is $\int_a^b f(x) dx$. The average value is the precise value k for which the function spends half the time below k and half the time above k .

Theorems about Definite Integrals. (Section 5.4) This section begins with the **Fundamental Theorem of Calculus**, which states that if f is continuous on $[a, b]$ and $f(t) = F'(t)$, then

$$\int_a^b f(t) dt = F(b) - F(a).$$

This provides a way of computing definite integrals exactly, by finding an appropriate $F(t)$. Such a function is called an **antiderivative** of $f(t)$. Theorems 5.2, 5.3, and 5.4 discuss **properties of the definite integral** which you should know, such as the fact that if c is a number in the interval $[a, b]$, and f is continuous on $[a, b]$, then we can split the integral like this: $\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$. In addition to the properties listed in these theorems, we also have facts about definite integrals when the integrand has even or odd symmetry. Specifically, if f is even, then $\int_{-a}^a f(x) dx = 2 \int_0^a f(x) dx$ for any a , and if g is odd, then $\int_{-a}^a g(x) dx = 0$ for any a . All of these properties can be proven using the definition of the definite integral as a limit of Riemann sums.